Lesson 7 Project Planning- Robot 1

**Robot 1**

Pick-up Coordinate Variable Names and Values

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Starting Value \_\_\_\_\_\_\_ Offset (-) \_\_\_\_\_\_\_\_\_\_

Drop Coordinate Values

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Delay Time in Seconds before it repeats the process (total time it takes the 2nd robot)

\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_