Lesson 7 Project Planning- Robot 2

**Robot 2**

Pickup Coordinate Values of product

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Coordinate Values for Color Sensor

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Coordinate Values for SPOT above each stamp

RED

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

BLUE

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Green

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Smudge prevention Drop Coordinate Values

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

Drop Coordinate Variable Names and Values for each PLACE location

Red

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Starting Value \_\_\_\_\_\_\_ Offset (-) \_\_\_\_\_\_\_\_\_\_

Green

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Starting Value \_\_\_\_\_\_\_ Offset (-) \_\_\_\_\_\_\_\_\_\_

Blue

X - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Y - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Value \_\_\_\_\_\_\_

Z - \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_ Starting Value \_\_\_\_\_\_\_ Offset (-) \_\_\_\_\_\_\_\_\_\_

Delay Time in Seconds before it repeats the process (total time it takes the 1st robot)

\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_