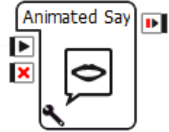
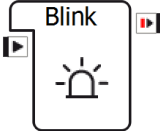
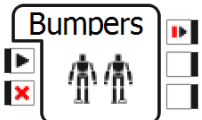
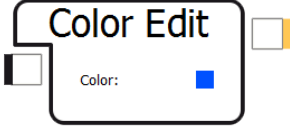
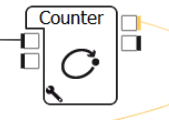
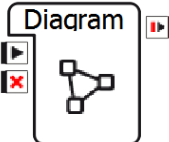
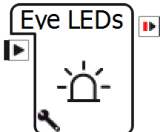
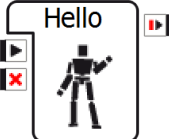
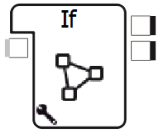

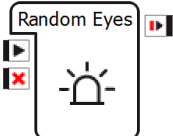
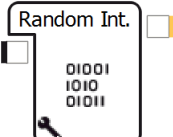
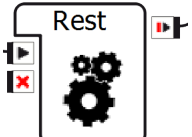
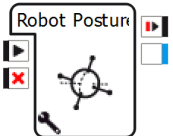

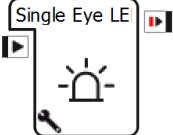
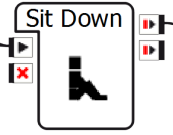



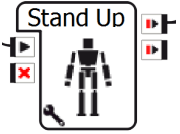
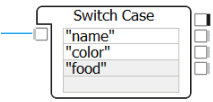
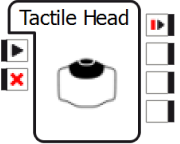
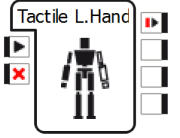
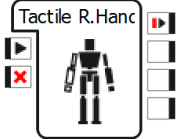
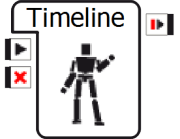
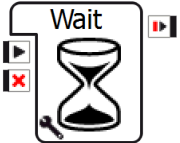

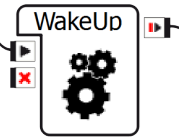
# Box GLOSSARY

Picture	Name	Function
	<b>ANIMATED SAY</b>	Makes the NAO speak while he moves his arms and head
	<b>BLINK</b>	Makes the robot blink once
	<b>BUMPERS</b>	Waits for one, or both, of the bumpers to be pressed
	<b>COLOR EDIT</b>	Sets a color and codes it as a number
	<b>COUNTER</b>	Makes NAO repeat an action a certain number of times
	<b>DIAGRAM</b>	A custom box to group other boxes
	<b>EYE LEDs</b>	Sets the LED color of both eyes
	<b>HELLO</b>	Makes NAO wave hello (He does not say hello)

# Box Glossary

Picture	Name	Function
	<b>IF</b>	Checks to see if the input is equal to a preset value
	<b>PLAY SOUND</b>	Plays a sound file through NAO's speakers
	<b>RANDOM EYES</b>	Changes the color of the eyes randomly
	<b>RANDOM INT.</b>	Chooses a random number from a range of numbers
	<b>REST</b>	Turns the motors off after putting him in a safe position
	<b>ROBOT POSTURE</b>	Outputs the name of the robot's current posture
	<b>SAY TEXT</b>	NAO says the text given to it through the blue input port
	<b>SINGLE EYE LED</b>	Sets the color of a single eye
	<b>SIT DOWN</b>	Makes the NAO sit down smoothly from any position
	<b>SPEECH RECO.</b>	Recognizes the word a human says from a particular list of words

# Box Glossary

Picture	Name	Function
	<b>STAND UP</b>	Makes the NAO stand up smoothly from any position
	<b>SWITCH CASE</b>	Changes tasks based on an input
	<b>TACTILE HEAD</b>	Detects a touch on the head
	<b>TACTILE L.HAND</b>	Detects a touch on the left hand
	<b>TACTILE R.HAND</b>	Detects a touch on the right hand
	<b>TIMELINE</b>	Makes NAO do a custom motion
	<b>WAIT</b>	Waits a certain amount of time
	<b>WAIT FOR SIGNALS</b>	Waits for both input ports to be signaled
	<b>WAKE UP</b>	Turns all of NAO's motors on